

OKLAHOMA STATE UNIVERSITY

SCHOOL OF ELECTRICAL AND COMPUTER ENGINEERING



**ECEN/MAE 5713 Linear Systems
Spring 2011
Final Exam**



Choose any four out of five problems.
Please specify which four listed below to be graded:
1) _____; 2) _____; 3) _____; 4) _____;

Name: _____

E-Mail Address: _____

Problem 1:

Find a minimal *controllable* canonical form realization (i.e., its simulation diagram and state space representation) for the following system described by

$$H(s) = \left[\frac{\frac{2s}{s^3 + 6s^2 + 11s + 6}}{s^2 + 2s + 2} \right]_{s^4 + 6s^3 + 9s^2 + 4s}$$

Problem 2:

Let

$$S = \{x \in \mathfrak{R}^3 \mid x = \alpha[1 \ 0 \ 2] + \beta[2 \ 0 \ 4], \alpha, \beta \in \mathfrak{R}\},$$

find the orthogonal complement space of S , $S^\perp (\subset \mathfrak{R}^3)$, and determine an orthonormal basis and dimension for S^\perp . For $x = [1 \ 2 \ 3] (\in \mathfrak{R}^3)$, find its direct sum representation (i.e., x_1 and x_2) of $x = x_1 \oplus x_2$, such that $x_1 \in S, x_2 \in S^\perp$.

Problem 3:

Find the state transition matrix of

$$\dot{x} = \begin{bmatrix} -\sin t & 0 \\ 0 & -\cos t \end{bmatrix} x.$$

Problem 4:

Let

$$A = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Find e^{At} .

Problem 5:

Consider

$$\dot{x} = Ax + Bu$$

$$y = Cx$$

and its adjoint system

$$\dot{z} = -A^T z + C^T v$$

$$w = B^T z$$

Show

$$H(s) = -H_a^T(-s),$$

where $H(s)$ and $H_a(s)$ are their transfer function matrices, respectively.